Temposonics®



Absolute, Non-Contact Position Sensors

L-Series Analogue + Digital

Temposonics® LD Measuring range 50 - 5000 mm

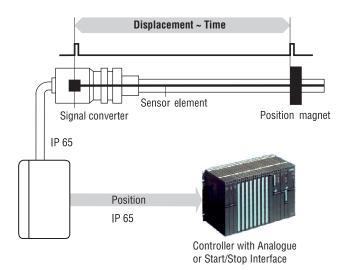


- Absolute Sensor
- Non-contact Measurement
- Modular Construction
- Stable Design
- Highest Durability
- Measuring Range: 50 5000 mm
- Linearity: Better 0,02 %
- \bullet Repeatability: 0,001 %
- Direct Analogue Output (V/mA): 100% field adjustable
- Digital Pulse Output, Start-Stop



Temposonics-LD

Analogue + Digital



The absolute Temposonics® linear position sensors are based on the MTS developed magnetostrictive measurement principle. That combines various magneto-mechanical effects and uses the physical hight precise speed-measurement of an ultrasonic wave (torsion pulse in its sensor element) for position detecting. The integral signal processing transforms the measurements into analogue or digital standardized outputs.

The *contactless* principle - an external movable magnet marks the position - eliminates the wear, noise and erroneous signal problems and guarantees the best durability without any recalibration.

Measured Variables Measuring Range

Output

Adjustment of NULL and SPAN Resolution

Linearity Repeatability Update Frequency Connection Type Input Voltage Current Drain

Ripple Temperature Coefficient Electric Strength Operating Temperature Dew Point, Humidity

EMV-Test

Shockrating
Vibration Rating
Mounting
Magnet speed
Sensor rod + flange
- Pressure Rating
Sensor Electronic Housing

Sealing

Sensor Installation Magnet Type Displacement 50 - 5000 mm

Voltage: 0...10 VDC or 10...0 VDC (Minimum load: > 5 kOhm) Current: 4(0)...20 mA or 20...4(0) mA

(Min/Max. 0 / 500 Ohm)

Start/Stop pulse: RS422 Differential signal Analogue: 100% of measuring range (F.S.) Analogue: Infinite, restricted by output ripple Digital: 0,1 mm; 0,01 mm (controller depending)

< ± 0,02 % F.S. (Minimum ± 50 μ m)

< ± 0,001 % F.S.

Analogue: 1kHz / Digital: controller dependent

Cable outlet 24 VDC (-15 / +20 %) 100 mA typical < 1 % peak to peak < 40 ppm/ °C

500 V (DC ground to machine ground)

-40 °C...+75 °C

90 % rel. humidity, no condensation

Electromagnetic emission EN 50081-2; Electromagnetic immunity EN 50082-2

EN 6100-4-2/3/4/6 Level 3/4 Criteria A, LD-sensor installed in a ground metal housing 100 g, 6 ms / IEC-Standard 68-2-27 10 g, 10 - 2000 Hz / IEC-Standard 68-2-6

Any orientation

Any

Stainless steel 1.4301 / AISI 304 350 bar, 700 bar peak pressure Aluminium diecasting housing

IP 65

Fitting flange or thread M18 x 1,5

Ring magnet

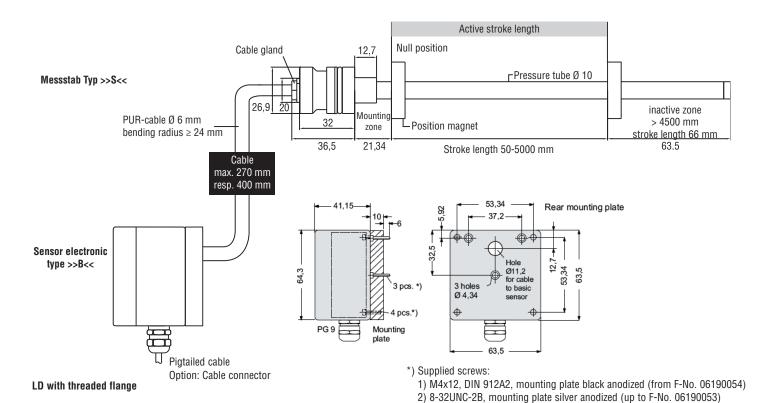
MTS Sensors I 2 I

Temposonics®-LD

The compact position sensor system was designed for installation in hydraulic cylinders, specifically for use in standard clevis head cylinders or any space limited cylinder applications.

- The pressure proof stainless steel sensor rod with fitting or threaded flange protects the sensing element in which gives rise to the measurement signal. It fits into the bored piston rod.
- The external standard industrial housing accommodates the modular electronic interface with active signal conditioning. The sensor electronic is connected to the basicsensor via inside terminal screws and to the controller with integrated cable outlet.
- The position magnet, the only moving part is mounted on the piston bottom.
 The permanent magnet travels wearfree and contactless along the stationary sensor tube. Its magnetic field starts the measurement signal through sensor's rod wall

LD with fitting flange



O-Ring 15,3 x 2,2 FPM75 (supplied) profile of screw boring see ISO 6149-1 Null position 23 across flats 25 Tightening torque < 50 Nm 26,92 Sensor rod type »M« 8 • inactive zone Thread Pressure tube Ø 10 > 4500 mm M18 x 1,5 PUR-cable Ø 6 mm stroke length 66 mm 32 bending radius ≥ 24 mm Mounting zone Stroke length 36,5 51 63,5 50 - 5000 mm Cable max. 270 mm resp. 400 mm *) Supplied screws see above Ф Rear view 4 pcs.*) Sensor electronic 53,34 64,3 64,3 type »S« 4 holes Ø 4,34 mm for mounting Pigtailed cable 53,34 Option: Cable connector 64,3

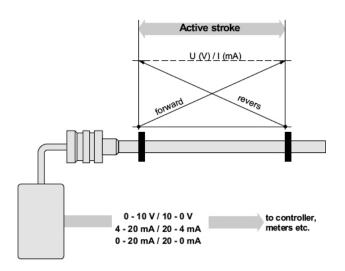
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Temposonics-LD

Analogue + Digital

Analogue Output

Temposonics® LD sensors provide direct analogue outputs, including voltage (0-10 V) and current (4-20 or 0-20 mA), forward and reverse acting. Resolution is only limited by the output ripple. Since the outputs are direct, no signalconditioning electronics are needed when interfacing with controllers or meters.



Sensor field programming

LD sensors are preconfigured at the factory by model code designation. If needed, MTS offers different external service tools for modifying sensor parameters inside the **active electrical stroke** (50 mm minimum clearance between setpoints) via the standard connection cable. There is no need to open the sensors electronics.

Following tools are available:

1. Handheld-Programmer G-Analogue

for setups of measuring length inside the ordered output by pushing up/down-buttons.



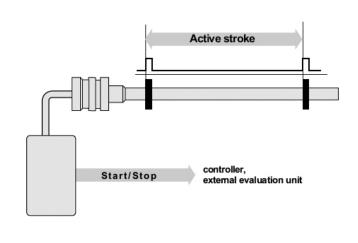
2. PC-Programmer G-Analogue

This hardware converter is required to communicate via serial port of Windows PC to the sensor. Customized settings are possible by using a MTS programming software (CD-ROM) for:

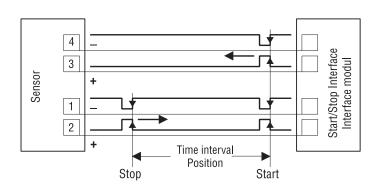
- 1. Null and Span
- 2. Forward and reverse acting
- 3. Output: Voltage/Current output values encl. range

Digital Start/Stop pulse

Digital LD sensor is equipped with a start/stop output. The sensor requires a start signal from an external indicator in onsite control system and returns a signal, corresponding to the magnet position. The time elapsed between the two signals is proportional to the magnet position, i.e. to the displacement. Time measurement is by the indicator and used for calculating the position value. Generation and evaluation of the start/stop pulse is made by a customized Start/Stop interface module of many controller companies.



Logic diagram Start/Stop



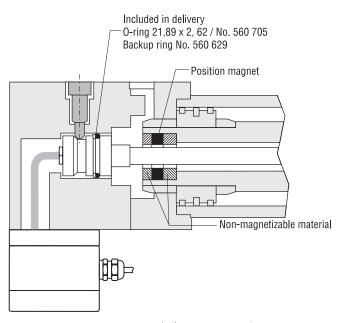
MTS Sensors I 4 I

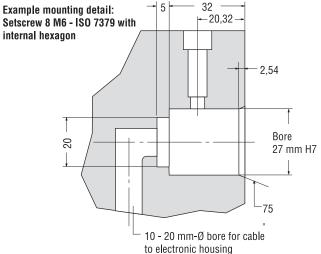
Cylinder installation

Temposonics® LD is designed for installation into hydraulic cylinders. Mounting of a LD sensor requires the use of a O-ring (black) and a backup-ring (orange). Both are supplied with the sensor. The sensor will be fixed via süecial screw. Interconnection cable

When mounted in the manner as shown below, interconnection cable is shielded according to EMC standard at the cylinder end cap. However, when the LD sensor is mounted in an alternative way, proper care must be taken to shield the interconnection cable.

Rod style »S« with Electronics Housing style Typ »B«





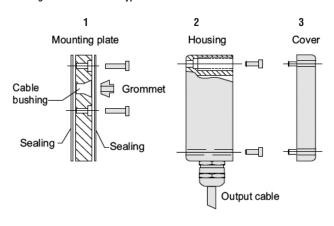
When installing the sensor in the cylinder notice following:

- · Magnet must not slide along the sensor tube.
- The bore in the piston rod and type of sealing ate determined by cylinder manufacturers as that depand on hydraulic pressure and piston velocity. We recommend 13 mm bore diameter at minimum. Do not exceed peak pressure.
- Protect sensor rod from wear.

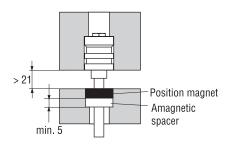
Mounting ring magnet

For accurate position measurements mount the magnet with non-magnetizable material (screws, etc.).

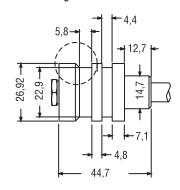
Monting Sensor electonic type »B«

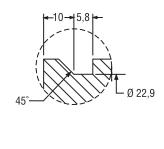


Minimum tolerances for magnetizable material



Detail: Flange

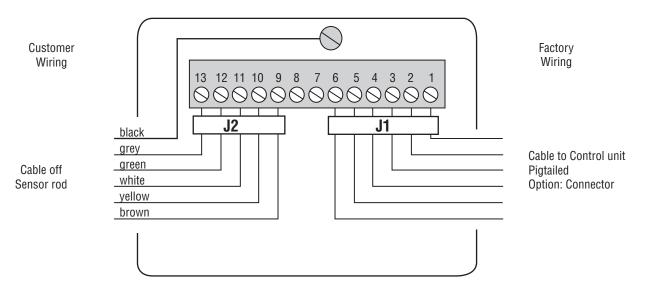






Only the mounting of sensorsystem as shown here fullfill the EMC standards of Electromagnetic Emission and Immunity.

Sensor Electronics Housing



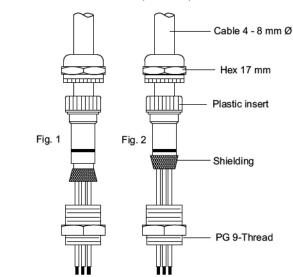
Terminal	Colour	Function
9	brown	V in
10	yellow	SE out
11	white	GND
12	green	WG (-)
13	grey	WG (+)
Screw	black	Frame GND



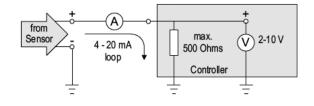
For side entry housing connect skield on EMC cable gland

Cable gland PG 9-EMC

EMC standard screwed cable gland for shielded cable. Simply to handle, as the cable shield must be removed backup over the plastic insert.



Typical 4 - 20 mA wiring



1. Start/Stop Output

Terminal	Colour	Function	Option:	Connector
1	white	DC Ground (0 V)	Pin 6	
2	pink	Stop (+)	Pin 2	
3	yellow	Start (+)	Pin 3	069
4	grey	Stop (-)	Pin 1	$\langle 2 = 4 \rangle$
5	green	Start (-)	Pin 4	3
6	brown	+24 VDC	Pin 5	Front view male insert

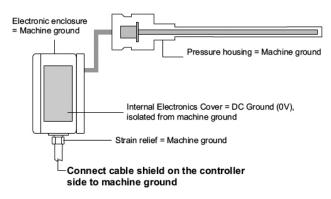
2. Analogue Output

Terminal	Colour	Function	Option: Connector
1	white	DC Ground (0V)	Pin 6
2	pink	DC Ground	Pin 2
3	green	PC Programmer only	Pin 4
4	grey	0-10, 10-0 V,	Pin 1 (065)
		4(0)-20, 20-(0)4 mA	(2 \(\)4 /
5	yellow	PC Programmer only	Pin 3
6	brown	+24 VDC	Pin 5 Front view male insert

Λ

Wiring of 10-0 V and 20-4(0) mA outputs is valid for LD sensors from fabrication # (F-No.) 0546 xxxx.

Typical Grounding





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 ${\bf Cable \ shield \ and \ DC \ Ground \ have \ to \ be \ isolated \ separately!}$

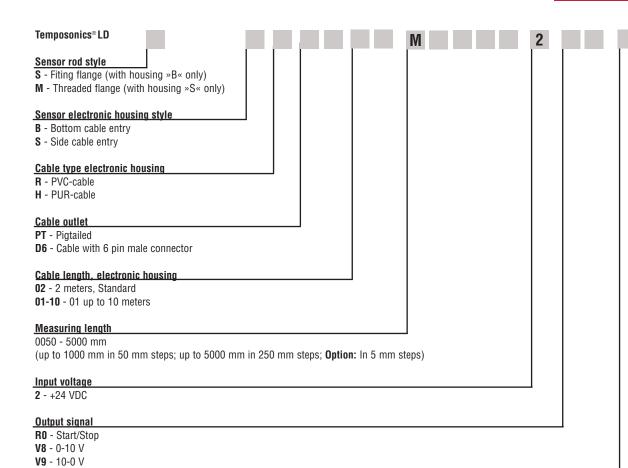
Lieferumfang:

- Sensorelektronik

Magnete und Zubehör

bitte extra bestellen.

Messstab



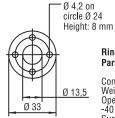
Integral cable length of Sensor rod

L1 - 270 mm

A4 - 4-20 mA **A5** - 20-4 mA **A6** - 0-20 mA **A7** - 20-0 mA

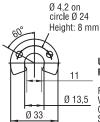
L2 - 400 mm

Position magnets (order seperately)



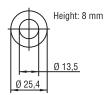
Ring magnet 0D33 Part No. 201 542-2

Composite PA-Ferrite-GF20 Weigth ca. 14 g Operating temperature: -40 ... +100°C Surface pressure max. 40 N/mm² Fastening Torque for M4 screws max. 1 Nm



U-Magnet OD33 Part No. 251 416-2

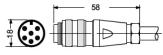
PA-Ferrit-GF20 Weigth ca. 11 g Operating temperature: -40 ... +100°C Surface pressure max. 40 N/mm² Fastening torque for M4 screws max. 1 Nm



Ring magnet OD25,4 Part No. 400 533

Composite: PA-Ferrite Weigth ca. 10 g Operating temperature: -40 ... +100°C Surface pressure max. 40 N/mm²

Male connector M16 wired on cable



6 pin DIN male connector Part No. 370 372

Housing: Zinc, nickel plated Termination: Solder Contact insert: Silver plated Cable clamp: PG 7 Cable-Ø: 6 mm

6 pin DIN female connector Part No. 370 623

Mating female connector M16

Accessories	Part No.
Ring magnet OD33, Standard	201 542-2
U-Magnet OD33	251 416-2
Ring magnet 0D25,4	400 533
6 pol. female cable connector M16	370 623
O-Ring 21,89 x 2,62	560 705
O-Ring 15,3 x 2,2 FPM	401 133
Backup ring	560 629

From F-No. 0546 xxxx LD-Analogue sensors are adjustable with following servicetools: Handheld-Programmer G-Analogue 253 294 PC-Programmer G-Analogue incl. power supply 253 145 (100-240 VAC/24 VDC), cable and programming software (CD)

All dimensions in mm

Temposonics-LD

Analogue + Digital

www.mtssensor.de www.temposonics-shop.de

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Deutschland

MTS Sensor Technologie
GmbH & Co. KG
Auf dem Schüffel 9
58513 Lüdenscheid, Germany
Tel.: +49-2351-9587-0
Fax: +49-2351-56491
info@mtssensor.de
www.mtssensor.de

IIS A

MTS Systems Corporation Sensors Division 3001 Sheldon Drive Cary, NC 27513, USA Tel.: +1-919-677-0100 Fax: +1-919-677-0200 sensorsinfo@mts.com www.mtssensors.com

Japan

MTS Sensors Technology Corp.
737 Aihara-cho,
Machida-shi
Tokyo 194-0211, Japan
Tel.: +81-42-775-3838
Fax: +81-42-775-5516
info@mtssensor.co.jp
www.mtssensor.co.jp